
mecarm Documentation

Release <https://github.com/dof2bot/mecarm/releases/>

Vladimir Roncevic <elektron.ronca@gmail.com>

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mecarm is 5.6 dof robotic arm.

mecarm is developed in C code: **100%**.

The README is used to introduce the tool and provide instructions on how to install the tool, any machine dependencies it may have and any other information that should be provided before the tool is installed.

INSTALLATION

Navigate to release [page](#) download and extract release archive.

To install **mecarm** type the following

```
in progress
```


DEPENDENCIES

mecarm requires next modules and libraries in progress

PROJECT STRUCTURE

mecarm is based on POP.

in progress

COPYRIGHT AND LICENCE

Copyright (C) 2020 by dof2bot.github.io/mecarm